

# SIGNALS

This kit is available from:

**Talking Electronics**

email Colin Mitchell:

[talking@tpg.com.au](mailto:talking@tpg.com.au)

for pricing and postage.



# SIGNALS

Signals that operate add a high degree of realism to any model railway as well as being something additional for viewers to watch. Unfortunately they are sometimes omitted due to the complexity of controlling them realistically. This article describes a module that can be readily fitted into an existing layout and used to control either two-aspect or three-aspect signalling systems. It can even provide a simple form of automatic train control by deadening blocks to prevent trains from running into each other.

On real railways, signaling systems are varied and complex depending on who designed them and where they are, but their primary purpose is always the same; to stop trains colliding with each other. On model railways their function is a little different. Sure, they can be used to stop trains colliding, but should this unfortunate event occur, the damage will be minimal, and there will be no loss of life (assuming you don't strangle the other @#\$\$ driver for wrecking your brass loco).

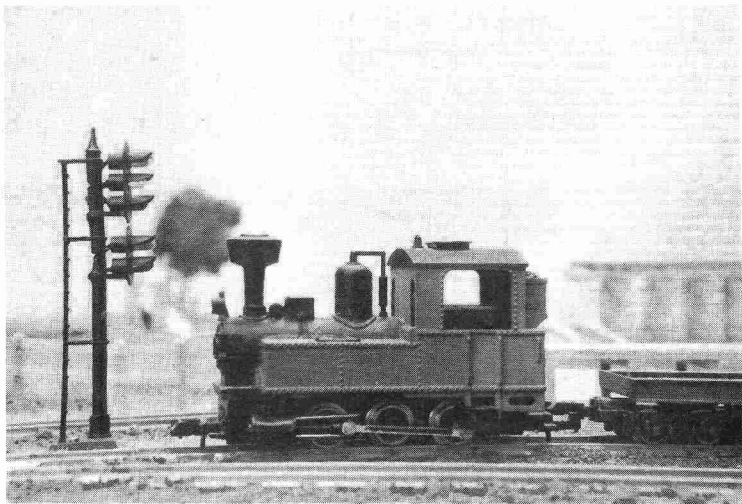
The second difference between real signalling systems and those on a model railway is the signal-man or lack thereof. Most model railways are operated either solo or on a one man per train basis, leaving no one to look after the signals. It is therefore fairly important that the signals be able to look after themselves. As I see it, the primary function of signals on model railways is to look the part, just like other items of scenery.

Most modellers will not be able to achieve an exact miniature of a real signalling system, due to the time and effort involved. The commercial signals that are available in most model shops are often not very accurate and being modelled after a type of signal used in another country they

are not really appropriate. Unless the individual wishes to make his own signals, he will have to settle for something that looks similar enough to fit the part. So with this in mind, I have developed a simple system using modules that can be used either as stand alone units or connected together, rather than attempting to exactly replicate a real system. They work with single direction traffic only. Two systems would be needed if they are to be used on a stretch of track that sees traffic in two directions. The system for the opposite direction would have to be switched off to stop it interfering with the one in use. My model railway has a preferred direction of travel because of the way the points have been laid out, so I have signals facing in only this direction.

I should point out here that for a three aspect signalling system, at least four modules are required. For a two aspect signalling system, three units are called for, but due to the stand alone nature of this circuit when used as a two aspect system, it is possible to use only one module.

The modules will drive either the bulbs used in commercial signals or LEDs. While I'm on the subject of LEDs and lamps, I feel it is a good idea to replace the grain of wheat



*A simple set of signals will add action and color to any layout.*

lamps in the signals with 3mm LEDs for several reasons. LEDs last a lot longer than lamps. In fact, under normal operating conditions, a LED should never burn out. The more common opaque LEDs give a much more even light than a lamp, and unlike lamps, there is no colored paint to chip off. LEDs draw about a quarter of the current, making less demands on the power supply. LEDs are shorter than lamps, and have a lens that looks the part. The final point of the argument is price. Last time I saw the price of a lamp, I couldn't believe it. They were about ten times the price of a LED!

## ABOUT THE CIRCUIT

The circuit consists of four basic parts. The first section is the train detector or sensor, which is mounted under the track between the rails. The second is the adjustable delay that controls the length of time on which the signal remains red. The third section of the circuit is the gate array that determines which light should be on, depending on the status of both the current and next blocks. The final section of the circuit drives the lamps and relay.

The first section to look at is the delay. It is the delay that makes these signals so easy to use. My original design used flip-flops to remember whether a train was in a block (section of track between signals) or not. There was no way that a train could creep into a block unless the train in front had reset it by moving into the block after it. This was fine, except for a couple of problems. All blocks had to be manually reset on occasion. A shadow passing over the sensor of an empty block was enough to lock the system. It was also very difficult to deal with trains that entered or

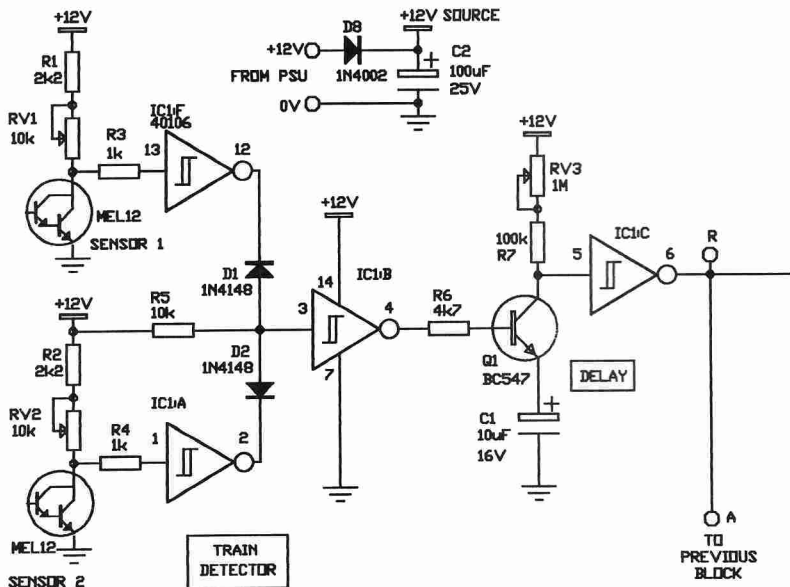
left the main line. By replacing the flip-flop with a delay, you achieve a very similar result without the above problems.

A train passing over a sensor will set the signal to red, and deaden the block behind it. The delay will be long enough for the train to reach the following block before the red period is over. Even if the train doesn't quite get out of the block in time, and the following train starts moving, it will not be long before the first train reaches the next signal and deadens the block behind it, once again maintaining a minimum distance of one block between the trains.

The only time there will be problems is if the first train comes off the track. The delay will eventually end and allow the following train to enter the same block, resulting in a collision if you don't stop it manually. Unless you are a speed maniac, or just love expresses, this should not worry you.

Each signal module has two optical sensors, one or both of which may be used. The first sensor is placed under the track, one locomotive length into the block (so the train doesn't stop itself!) The second may be placed further along if the block is exceptionally long. If you have two lines coming to a junction, a sensor can be placed in each line and the whole junction made one block, ensuring that only one train can approach the set of points or crossing at a time. If you do not require the second sensor, place a link on the PCB where the second sensor would normally be connected. Failure to do this will result in the unit permanently staying red.

The sensors use a MEL12 darlington photo-transistor as the active element. Light falling on the junction of the first transistor in the darlington pair has the same effect as



The circuit diagram of the signal module.

applying a voltage to the base of the device. It turns the transistor on. The degree of saturation, or how hard the transistor pair is turned on, depends on the intensity of the light.

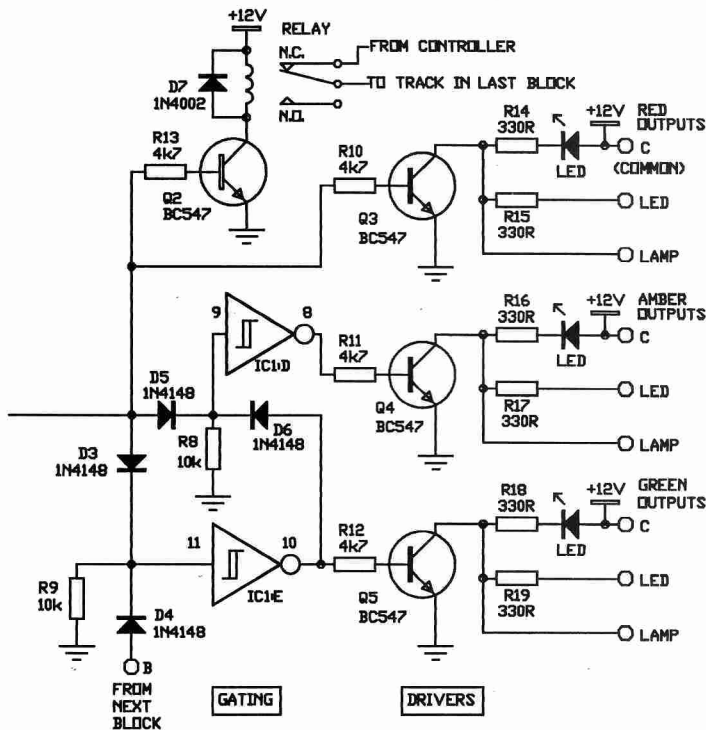
Therefore when light is falling on SENSOR 1, it will hold the input of the schmitt inverter IC1:F (pin 13) LOW via R3. When a train casts a shadow over the MEL12, the transistor will not be turned on as hard, allowing its collector to be pulled up by R1 and RV1. When RV1 has been adjusted correctly, the voltage at this point will rise over the input threshold of the schmitt inverter IC1:F (about 2/3 of the voltage on which the chip is being run, in this case 8 volts) and its output will go LOW (to 0 volts).

I should also mention here that these sensor circuits behave quite differently under various light conditions. They are very sensitive under fluorescent lights, but under incandescent lamps, they are harder to trip. If you find you have problems, you may need to change R1 and R2. Reduce them if you can't make the signals go red, or increase them if the signals won't return to amber or green. When you are making the adjustments, the delay can be disabled by leaving C1 off the board or shortened by clipping a 1k resistor between the 12 volt rail and the collector of Q1.

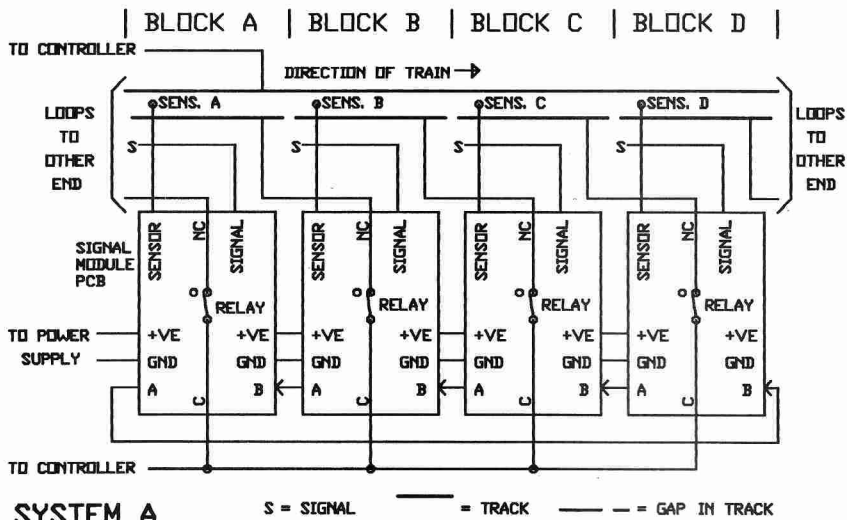
D1, D2, R5 and IC1:B form a NAND gate. When a shadow falls on either of the sensors, the NAND gate's output will go HIGH (to 12 volts), switching on Q1. This will discharge C1, sending the output of IC1:C HIGH. When the train is no longer over either of the sensors, the output of IC1:B will go LOW again, switching off Q1. C1 will charge through RV3 and R7. When the voltage on the capacitor reaches the input threshold of IC1:C the output will revert to being LOW.

Whenever the output of IC1:C is HIGH, Q2 and Q3 are turned on, pulling in the relay and lighting the red LED. The inputs of IC1:D and IC1:E are both jammed HIGH by diodes D3 and D5. This ensures that both Q4 and Q5, and thus the amber and green LEDs, are off. The output of IC1:C is also sent to the signal module controlling the previous block.

If you look at the diagrams on the following pages, you will see that there are several ways in which the signal modules can be wired. Each method had advantages and disadvantages. Choice of the most suitable depends on which advantages you prefer.



The circuit consists of four major blocks: Detectors, Delay, Gating and Drivers. Each is explained in the text.



## SYSTEM A

This diagram shows the simplest way to connect the signal modules together. This is the system that is described in detail in the text. The diagrams on the following pages show more complex, but more realistic ways to wire the modules.

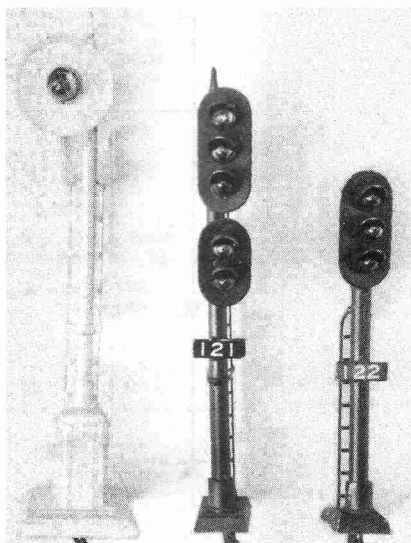
We will now look at three blocks to describe how they interact. The blocks are in the order A, B, C. See the diagram marked "System A". The train has just left block B, entering block C. The signal at the start of block C has just gone red.

The train had tripped the sensor and output of the delay in block C is HIGH. It turns on the red lamp driver and the block deadening relay driver, switching off power to the track in block B, while jamming the green and amber drivers off via D3 and D5. The output of the delay is also sent to the previous signal module, in block B.

The output of the delay in the block B module would now have gone LOW again. This enables the amber and green gating. The delay output of block C (still red) will now select the amber light at this signal by jamming the green driver off via D4. Note that even though the lamp has gone amber, a train may not proceed into block B because the block is still deadened by the relay in the block C module. However, because the module in block B is not RED, a train may move into block A.

Back at block A, it has been a long time since its delay went low, enabling the amber/green gating. As the delay output of block B is now also low, the block A signal will display green. The output of IC1:E jams the amber light off via D6. This is the natural or "rest" status for a signal module.

This is the system that I prefer because of its simplicity, but some may not like the idea of a train sitting at an amber light. There are a couple of solutions. One way is to move the actual signals one block ahead, to the beginning of the section of track they control. See the diagram marked "System B". This has the disadvantage that a signal will remain green as a train passes it changing to red only when the train reaches the next signal. I would not recom-



A few of the signals available commercially. The two spare lamps on the five lamp signal may be driven by the station signal project later in this book.